

University Rover Challenge 2012 – Requirements and Guidelines

Any issues not covered by these published rule sets will be addressed on a case-by-case basis by the University Rover Challenge (URC) Director. Please consult the Questions and Answers (Q&A) portion of the URC web site (<http://urc.marssociety.org/home>) for updates. All matters addressed in the Q&A are applicable to the requirements and guidelines.

1. Competition Overview

- 1.a. The 2012 University Rover Challenge will be held May 31st – June 2nd, 2012 at the Mars Society's Mars Desert Research Station (MDRS) near Hanksville, Utah.
- 1.b. The rover shall be a stand-alone, off-the-grid, mobile platform. No tethers will be allowed during its operation for connection to external sources.
 - 1.b.i. A single connected platform must leave the designated start gate and return to this location (except when otherwise indicated). In the open field, the primary platform may deploy any number of smaller sub-platforms, so long as the combined master/slave sub-platforms meet all additional requirements published.
 - 1.b.ii. Any airborne vehicles must meet any and all FAA (United States Federal Aviation Authority) guidelines that apply to operating unmanned aircraft in a remote area. It will be the responsibility of each team to research any such FAA requirements and provide documentation to the judges prior to April 27, 2012.
- 1.c. Teams will operate their rovers from designated command and control stations. These stations will be tents with tarp walls restricting visibility of the course (to be provided). Basic power (120V, 60Hz), tables, and chairs will be provided. Metal trailer units (such as the back of a small moving truck) may be provided in place of tents.
- 1.d. There is no restriction on the number of operators allowed, as long as all operators remain in the designated operators' area. Nobody may follow alongside the rover and radio back any information. Members of the judging team may follow a rover at their discretion.
- 1.e. The GPS standard shall be the WGS 84 datum. Teams shall adhere to this standard. Coordinates will be provided in latitude/longitude format (degrees/minutes).
- 1.f. The MDRS field site is located in the desert of southern Utah. As such, the site will have a full spectrum of sloped terrain from flat to vertical. Teams should be prepared for any ground conditions that would appear at MDRS (please consult the MDRS web site – <http://mdrs.marssociety.org/> – for field reports, images, and other resources). Except for when noted in this document, the objective sites shall be reachable by paths of no greater than a 15% slope. The rover shall also be capable of withstanding such an environment in the early summer, including airborne dust and temperatures that can easily reach 100°F. Although it is improbable, rovers shall be able to withstand extremely light rain. Rovers will not be expected to compete in heavy rain or thunderstorms.

2. Rover Guidelines

- 2.a. Rovers shall utilize power and propulsion systems that are applicable to operations on Mars. Air-breathing systems (such as internal combustion engines and certain fuel cells) are permissible, but only under the following criteria:
 - 2.a.i. The team shall design an air supply system that would be compatible with the subject air-breathing system, and would operate at a reduced air pressure. The design must provide sufficient air that the capacity of the fuel tank is the primary energy limitation.
 - 2.a.ii. The team shall provide a full list of off-the-shelf components that would satisfy the design. This system design and specification must include an estimate of cost and weight.
 - 2.a.iii. This design and specification shall be submitted to the URC Director and Judges for final approval no later than April 27, 2012. The cost and weight estimates may be revised by the URC Judges, with the approval of the URC Director, in which case the revised numbers will be communicated to the teams by May 4, 2012. Teams may appeal these revisions no later than May 11, 2012.
 - 2.a.iv. A final cost and weight of the air supply system shall be assessed against the rover's budget and weight allocations as defined in these rules.
 - 2.a.v. Due to safety considerations, teams shall not implement any such systems.
- 2.b. The maximum allowable mass of the rover when deployed for any competition event is 50 kg. This mass does not include any other hardware used to prepare or maintain the rover, any spare power sources not being used, or any additional rover configuration components not on-board for the particular competition event.
 - 2.b.i. For each event in which the rover is overweight, the team shall be assessed a penalty of 10 points, plus 1 additional point per kilogram over 50.
 - 2.b.ii. Rovers over 75 kg in any given configuration must be cleared with the URC Director by email prior to April 27, 2012 to be eligible to compete.
 - 2.b.iii. The combined mass of spare power sources and additional rover configuration components shall not exceed 20 kg.
 - 2.b.iv. There will be no weight limit imposed on command and control team equipment, base communications equipment or maintenance tools.
 - 2.b.v. If a gas-consuming engine is used, the rover shall weigh-in with all tanks full.
- 2.c. Wireless communication methods used by teams shall adhere to all applicable FCC (United States Federal Communications Commission) standards and regulations. Teams must submit details regarding any wireless communication devices being implemented and operator licenses (when applicable) to the URC Director no later than April 27, 2012. Teams must notify the URC Director immediately of any changes after this date. Teams may be required to power down communications equipment at the event sites while not competing, so as not to interfere with other teams.
- 2.d. Communications equipment must not rely on the team's ability to watch and track the rover first hand. Equipment may be directionally steered if kept inside the command and control tent. Any communications equipment outside of the tent shall be stationary.

- 2.d.i. Teams may have a member visually track the rover and rotate/steer communications equipment placed outside of the tent. This person may not communicate with the rest of the team inside the tent, and will result in a penalty of 10 points per event utilized.
 - 2.d.ii. The stationary requirement does not impose mechanical rigidity, just a rigid, stable base. An automated azimuth-finding antenna is permissible, as long as it is safe and stable. Electrically steered antennas are also permissible, as long as they are operated within FCC regulations (as applicable).
 - 2.d.iii. Antenna bases must be located within 5 meters of the team's command and control tent, and shall adhere to all applicable regulations. Any such antenna must be documented as part of the communications documentation deadline. Any ropes or wires used for stability purposes only may be anchored within 10 meters of the command and control tent.
 - 2.d.iv. Tethered lighter-than-air devices cannot be used for direct observation or reconnaissance, however can be implemented for communications. Such devices must be safely anchored within 5 meters of the command and control tent, and may not drift more than 10 meters from the overhead space of the command and control tent. All safety precautions, and applicable FCC and FAA regulations, must be documented as part of the communications documentation deadline.
- 2.e. Teams will be guaranteed a 1.5 km minimum separation between competition areas, which will include large terrain barriers. Event scheduling will avoid communication interference to the greatest extent possible. Teams will be notified of all frequencies being used by other teams, and will be required to deconflict when a conflict occurs (the URC Director will mediate as necessary). Because of this, teams are encouraged to work with equipment that maximizes channel flexibility.
- 2.f. The rover is not required to be autonomous. However, it shall be operated remotely by a team which will not be able to view the rover on the site or the site itself directly. The rover may be commanded by the team using a wireless link, with information needed for guiding the rover acquired by the rover's own on-board systems and transmitted to the team wirelessly. There shall be no time delay in communications, as the URC is based on the assumption that the rovers in question are telerobots, being operated by astronauts on or orbiting Mars. Refer to rule 3.g regarding the impacts of a loss of communications.
- 2.g. If the rover or any of its subsystems are an airborne vehicle that is not lighter-than-air, it must, in addition conforming to rules 1.b.i and 1.b.ii, simulate a vehicle that could fly on Mars. While the ground level air density on Mars is much lower than on Earth, the gravity is lower too. In order to simulate these effects on Earth the vehicle shall carry a dead weight equal to the weight of the battery(s) used. For example, if the airborne vehicle is powered by a battery that weighs 50g it must carry a dead weight of 50g. Teams shall provide the dead weight(s) and may distribute it (them) as they see fit, provided that the dead weight and battery(s) are removable from the vehicle so they may be weighed. A dead weight shall not provide power, add structural or aerodynamic support, perform computation or sensing, or otherwise add functional utility to the system.

- 2.h. Lighter-than-air vehicles are not allowed at URC since lighter-than-air vehicles on Mars are only practical for heavy lift applications.

3. Competition Tasks

- 3.a. The rover shall be judged in the four competition tasks outlined below in 3.b-e, in addition to the presentation task outlined in 3.h. The five tasks will be independent events.
 - 3.a.i. For the four competition events, the rover is not required to be in the same configuration. Teams will have at least 2 ½ hours to reconfigure, adjust and repair their rovers in between competition events, and will not have to compete in more than 2 such events in a single day.
 - 3.a.ii. Each event, including the presentation task, shall be worth 100 points, for a total of 500 points. The minimum points awarded for a single event is zero (even if the penalties are greater than the points earned).
 - 3.a.iii. For all competition tasks except the Astronaut Assistance Task, rovers are required to return to the start gate within the time allotted.

3.b. Site Survey Task:

Teams shall be required to perform a remote survey to determine the precise coordinates (to include altitude) of field markers that are not reachable by the rover. Teams will be provided with a map of the local region, which will include the precise coordinates of major visible landmarks. Rovers shall have to drive up to 0.8 km to reach an observation position (approximate coordinates to be provided) from which it will have a line of site view of the targets. Target markers will consist of white PVC pipes no less than 10cm in diameter, standing vertically from the ground to a height of 1-2 meters. A white flag measuring at least 15cm (vertically) x 30cm (horizontally) will be attached to the top of the marker. Some of the markers will include markings and other designations in the visible spectrum. At the completion of the on-course run, teams will be asked specific questions about any such designations that the rovers observed. Such markings shall be no smaller than 3mm x 3mm per 100m of anticipated standoff distance (targets at 800m may contain markings no smaller than 24mm x 24mm). Questions based on these markings shall account for no more than 40 percent of the weighting for this task. Teams will be required to survey markers located up to 1.0 km from the given observation position. Teams will not be told the number, or general location, of any markers. Teams will have 30-50 minutes of on-course time, followed by 10-15 minutes to perform calculations and analysis (exact amounts of time to be announced on-site). Scores will be based on the number of targets identified, the accuracy for each of those localizations, and the ability to respond to questions relating to the aforementioned markings.

3.c. Sample Return Task:

Teams will be given a field briefing by judges to discuss the task site. Teams controlling their rovers shall then select multiple (3-6) sites of potential biological interest within a 0.8km radius of the start gate. Based upon investigation of the selected sites, teams shall then collect and return a single sample from the site they determine to have the greatest likelihood of containing photosynthetic bacteria such as cyanobacteria/blue-green algae,

other bacterial colonies such as are associated with desert varnish, as well as other nonbacterial extremophiles such as lichen. The mass of this sample must be at least 25 grams, but no greater than 250 grams, and may consist of a single rock, or a soil sample. The primary indicator of the extremophiles of interest is reflected light in the visible spectra. Teams may supplement this with secondary observations in the infrared spectra, or minimally-invasive direct measurements at their discretion (teams must be prepared to describe and defend all forms of analysis implemented). Rover shall return the collected sample to the team's command and control tent by the end of the time allotted.

Teams shall document each site investigated according to the Remote Science Documentation Procedure described below. Teams will be given 30-60 minutes to collect data and the sample with the rover (exact amount of time to be announced on-site), after which they will be given a similar amount of time (not necessarily equal to the on-course time) to prepare data for a field briefing to the judges (which will last 15 minutes, to include questions from the judges). In the field briefing to judges, teams will be required to describe and analyze their data for all sites investigated, and provide a justification for returning the sample that was selected. The score for this task will be based on the following, equally weighted, components: 1) thoroughness of the investigation of sites; 2) quality and applicability of the analysis of the field science; 3) quality of the sample returned; and 4) quality and applicability of the analysis of the sample returned.

Remote Science Documentation Procedure:

For the Sample Return Task, teams shall follow these guidelines at each site. At a given site, the team shall take a close up, high-resolution picture with some indication of scale (scale can be indicated post-capture). The team shall then produce a wide-angle panorama showing the full context of the site and immediate surrounding area. The panorama must indicate cardinal directions, and have some indication of scale. Teams must also record the detailed GPS coordinates of each site, to include elevation and accuracy range. Thorough documentation is especially crucial for the sample that is returned.

3.d. Astronaut Assistance Task:

Teams shall be required to deliver multiple supply containers to simulated astronauts in the field as quickly as possible. There will be 2-5 astronauts in the field at distinct locations (the exact number will be announced on-site). The astronauts will be identifiable by simulated space suits, which may be in a variety of positions. Approximate GPS coordinates will also be given for each astronaut.

The supply containers (to be provided on-site) shall be no smaller than 15cm x 10cm x 10cm, no larger than 30cm x 15cm x 15cm, weigh no less than 0.5kg and no more than 6kg, be orientation independent, and will be covered in the loop portion (i.e. – the soft side) of a VELCRO style fastener (which teams may utilize to secure the box to the rover). Each distinct container may be of a different size, and will each be visually designated for a particular astronaut. Any or all of the containers may be loaded on to the rover by team members before the clock starts, or may be picked up by the rover in front

of the command and control tent after the clock starts. The supply containers must be delivered, and deployed, to within 1m of the respective astronaut.

A maximum time limit between 30 and 60 minutes, and approximate GPS coordinates (to within 25m) for the astronauts, will be provided to teams. All astronauts will be located within a 1.0 km radius of the start gate. Line of sight communication with the start gate will only be guaranteed for 25% of the course. While it will be possible to reach at least one of the astronauts by traversing moderate terrain (less than 15% slope), it will only be possible to reach all astronauts by traversing terrain as steep as a 50% slope. One to two astronauts will be intentionally located where line of sight communication with the start gate will be occluded by the terrain. These astronauts will be visible from points within line of sight communication with the start gate, and accessible from such points via benign terrain and a distance of no greater than 150m. Accurate GPS coordinates (to within 3m) will be provided for the hidden astronauts. Scores will be based on speed of delivery, completion of container deployment, and number of astronauts reached. For this task the rover is not required to return to the start gate; however the rover may make multiple trips to/from the start gate to retrieve additional containers.

3.e. Equipment Servicing Task:

Rovers shall be required to perform several dexterous operations on a solar panel and mock-up equipment panel. The rover will have to travel up to 0.5km across relatively flat terrain (negligible slope) to reach the panel. Teams and their rover shall then have to read directions, printed on the panel, describing the sequence of tasks to be performed. Tasks shall include measuring voltage across exposed terminals, cleaning a solar panel, reading meters, pushing buttons and flipping switches.

In particular teams will be required to measure the voltage from the solar panel and if it is below a critical level clear dust and mud from the panel then recheck the voltage. Some of the dust will be lightly coating the panel, but some may be caked on and need more effort to remove. The solar panel will be less than 50 cm x 50 cm and be mounted horizontally less than 50cm above the ground. The voltage may be read from nails sticking up 2.5cm from a horizontal panel and spaced 2.5cm apart.

The equipment panel will be vertical, and all items of interest (including text) shall be located between heights of 15cm and 75cm above the ground. From the most forward point of a particular section of panel, the depth to any item of interest shall not exceed 45cm. All text on the board shall be printed in the equivalent of Times New Roman 18 point font in black ink against a white background. Teams will receive points for every sub-task completed successfully, however will be partially penalized for subtasks completed out of order. Sub-task point weights will be consistent with the level of difficulty (i.e. cleaning the solar panel will have the largest weight, pushing buttons the smallest weight).

3.f. From the time teams are given access to their command and control tent, they shall be able to set up all necessary systems, including all communications systems, and be ready

to compete in no more than 25 minutes. Teams shall be able to fully disassemble all equipment in no more than 15 minutes at the end of the event.

- 3.g. If a rover suffers a critical problem during a task that requires direct team intervention (including a loss of communication that requires the team to move the rover to reestablish communications), that intervention shall be subject to the following:
- 3.g.i. The team may designate any number of members (herein referred to as “runners”) who may retrieve the rover, and return it to the blind side of the command and control station (such that the other members may work on the rover without being able to view the task site).
 - 3.g.ii. Runners shall not communicate any details about the task site to the rest of the team (judges will monitor conversation), however are permitted to take part in the diagnostic process.
 - 3.g.iii. After completing work on the rover, the runners may relocate the rover to any position within the start gate area.
 - 3.g.iv. The runners shall not be permitted to participate in the command and control of the rover, or analysis of any data, after this point for the current event. Runners will still be permitted to retrieve the rover in future interventions, although only at the direction of the eligible command and control team.
 - 3.g.v. Teams will be penalized 10 points for every intervention. The task clock will continue to run during interventions.
- 3.h. Presentation Task:
Teams shall prepare and deliver a presentation to the URC judges describing their team, rover design and functionality. The length of the presentation (not including questions) shall be no longer than 15-20 minutes (exact time limit will be announced no later than May 18, 2012). Judges may ask follow-on questions as warranted after this time. Scoring will be assessed on the following equally weighted categories:
- Team structure, organization, and management
 - Core rover design and presented functionality (rover need not function for presentation)
 - Suitability of rover design to competition tasks
 - Response to follow-on questions
 - Overall quality of presentation

4. Team Management

- 4.a. Teams shall be required to track all finances as related to this project, and submit a final expense record no later than May 25, 2012 (if necessary, teams may submit an updated record – hard or soft copy – on the first day of the URC event – May 31, 2012). Teams shall be penalized 25 points per day if they are late in submitting the expense report, and will be disqualified for not submitting their expense report by the end of the URC event.
- 4.a.i. The maximum allowable cash budget to be spent on the project is \$15,000 US, which shall include money spent on parts and components for the rover, rover modules, rover power sources, rover communications equipment, and base station communications equipment (only that equipment used to communicate with the rover). The budget limit shall not apply to command and control equipment not

- included above (i.e. base station computers and monitors), tools, volunteer labor time, or travel expenses.
- 4.a.ii. Teams may acquire in-kind donations of equipment. Such donations will count towards the cash budget at its documented value. Corporate sponsorship is encouraged.
 - 4.a.iii. Teams may be required to submit receipts as proof of budget upon request (donations must be documented by the donor).
 - 4.a.iv. Any parts and/or components purchased in previous years and/or leveraged from previous rovers or projects for the URC 2012 rover shall be valued at purchased prices unless teams elect to document the current newly purchased value of all components.
 - 4.a.v. If teams elect to document the current value of all components they may apply United States Internal Revenue Service depreciation rules to 50% of their re-used components. In the case of discontinued or outdated components, the price of a reasonable substitute must be documented.
 - 4.a.vi. International teams have an allowable budget equivalent to \$15,000 US based on the most advantageous documented currency conversion rate between August 1, 2011 and May 31, 2012.
- 4.b. There shall be one division of competition open to both graduate and undergraduate students. Teams shall be permitted to include secondary school (high school) students. A single university may field multiple rovers and multiple teams, however there may be no overlap between team members and leaders, budget, donated equipment, or purchased equipment.
- 4.c. Teams are encouraged to work with advisors. However, advisors are expected to limit their involvement to academic level advising only. It is incumbent upon the student team leaders to ensure that their respective teams uphold the integrity of this competition. Nontechnical team management duties, including tracking finances, fall within the duties of the students.